

A Generic Model of Cell Cycle Regulation in Eukaryotes

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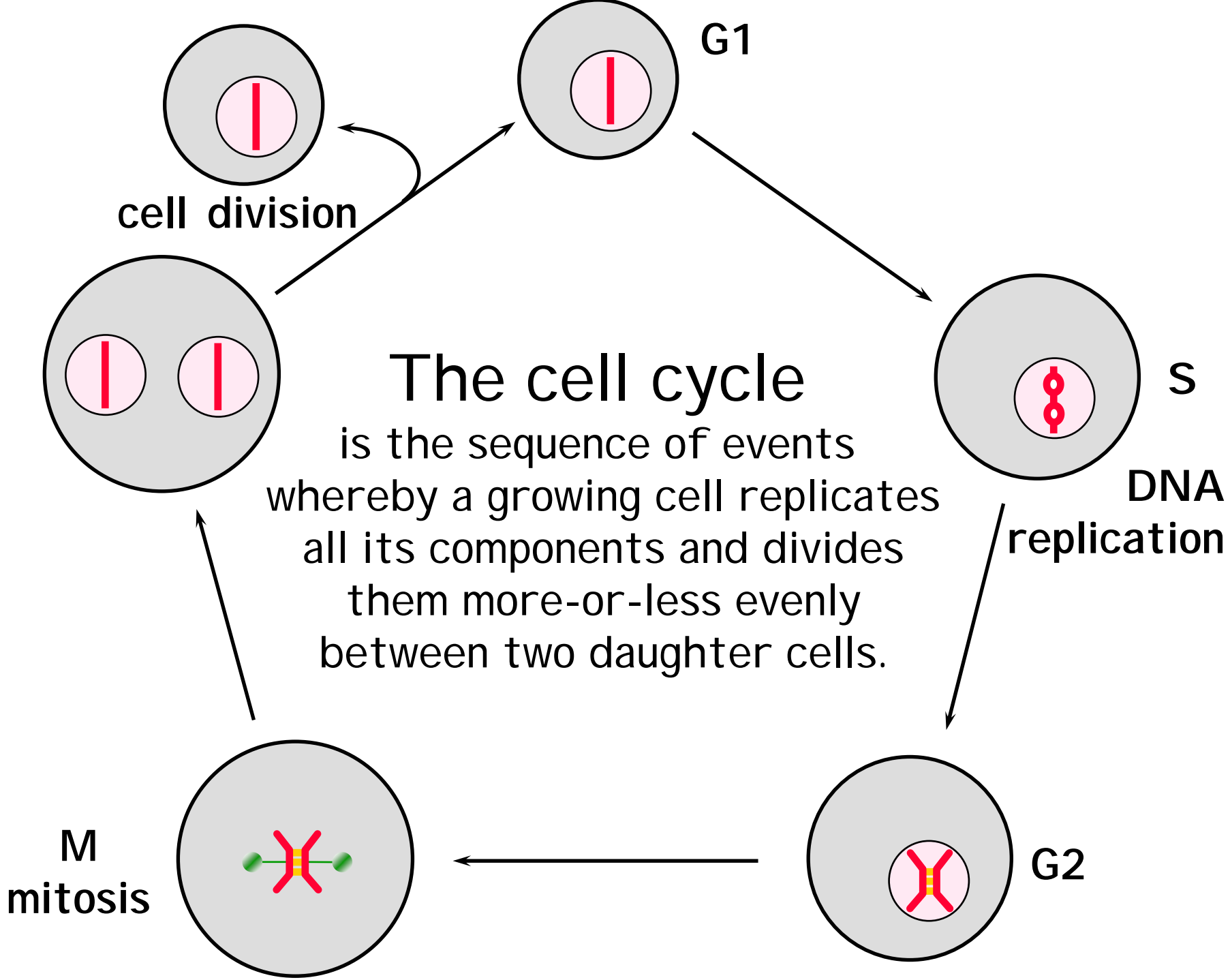
Virginia Polytechnic Institute & State University

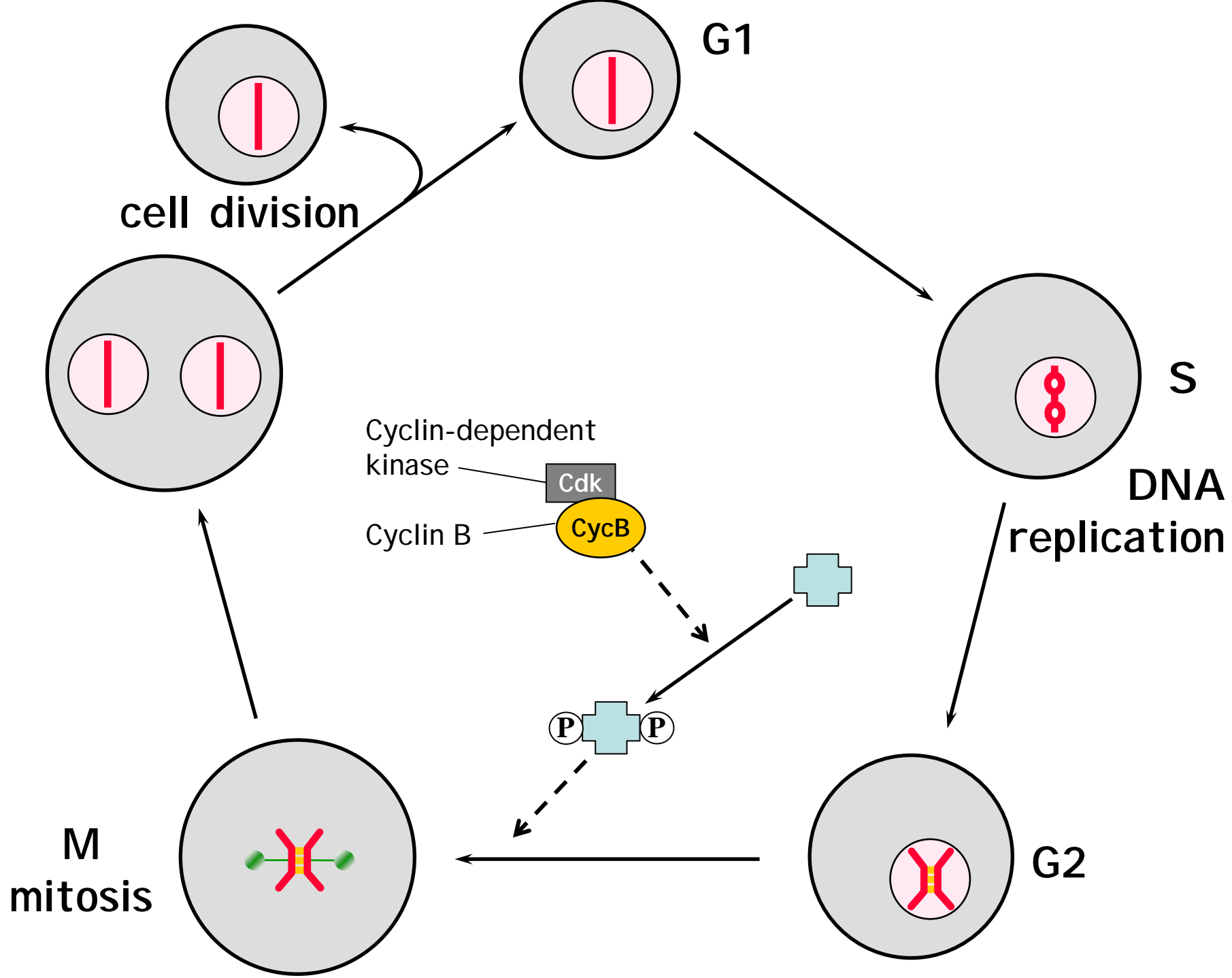
Financial Support

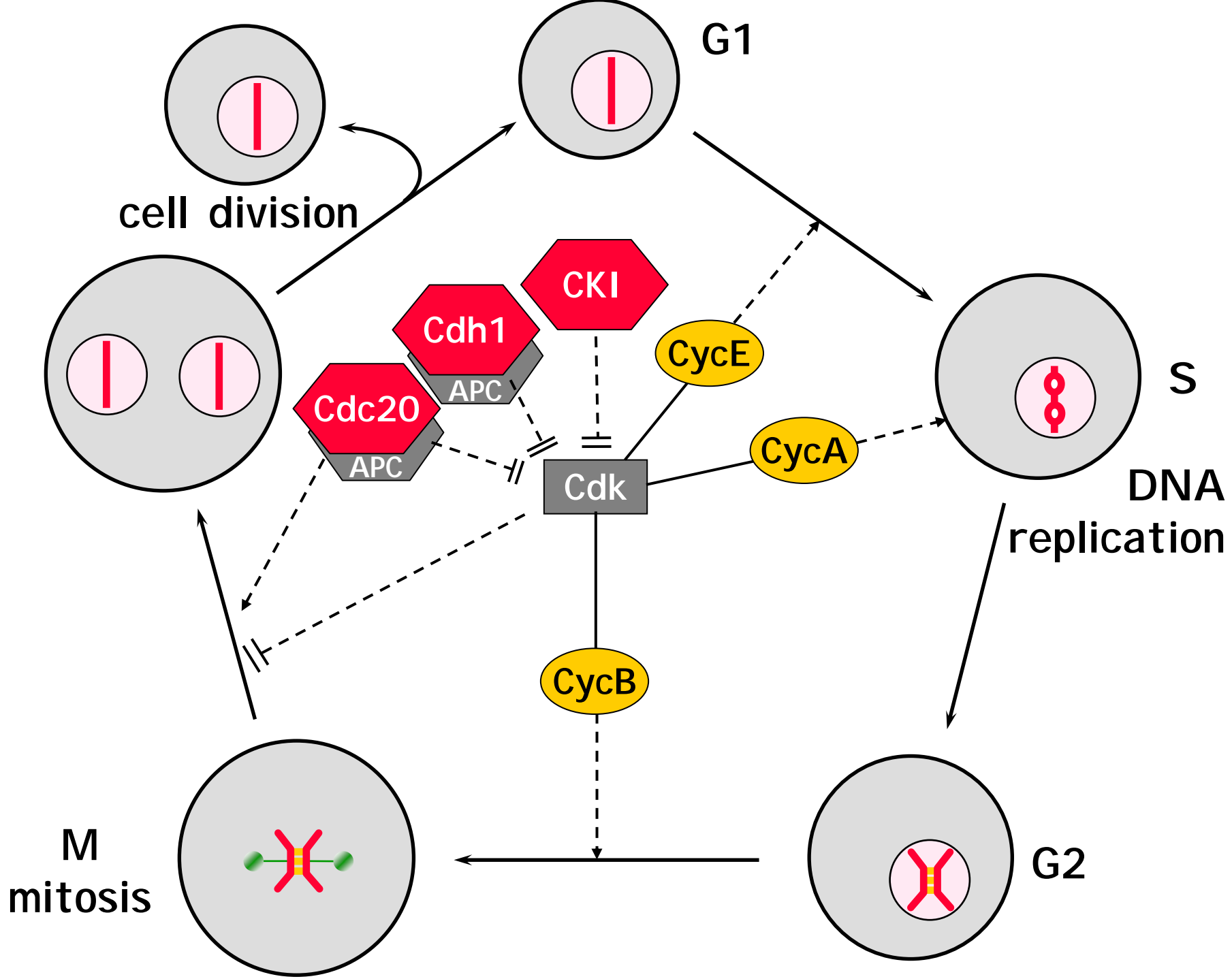
- 💰 Defense Adv. Res. Project Agency
- 💰 National Institute of Health
- 💰 James S. McDonnell Foundation

Cyclic & Dynamic Behaviors

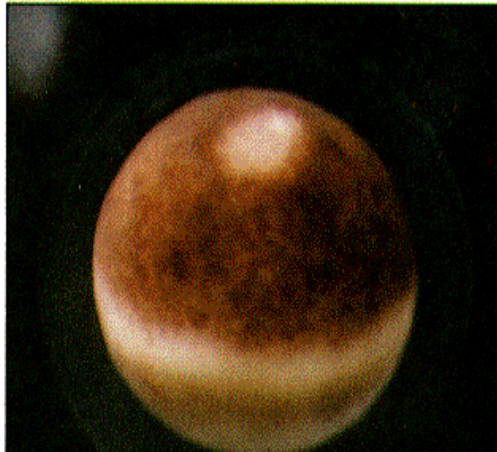
Neural oscillations	0.01-1 sec
Calcium oscillations	1-100 sec
Hormonal rhythms	min - hours
Cell cycle	hours - days
Circadian rhythms	1 day



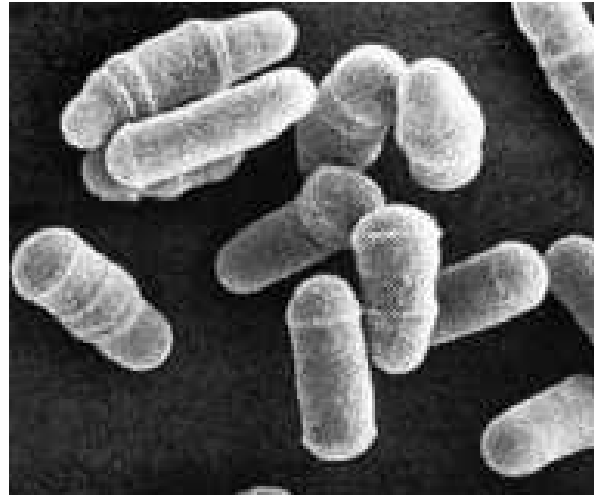




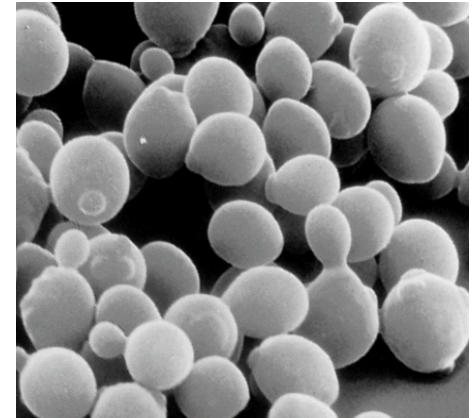
Frog Egg



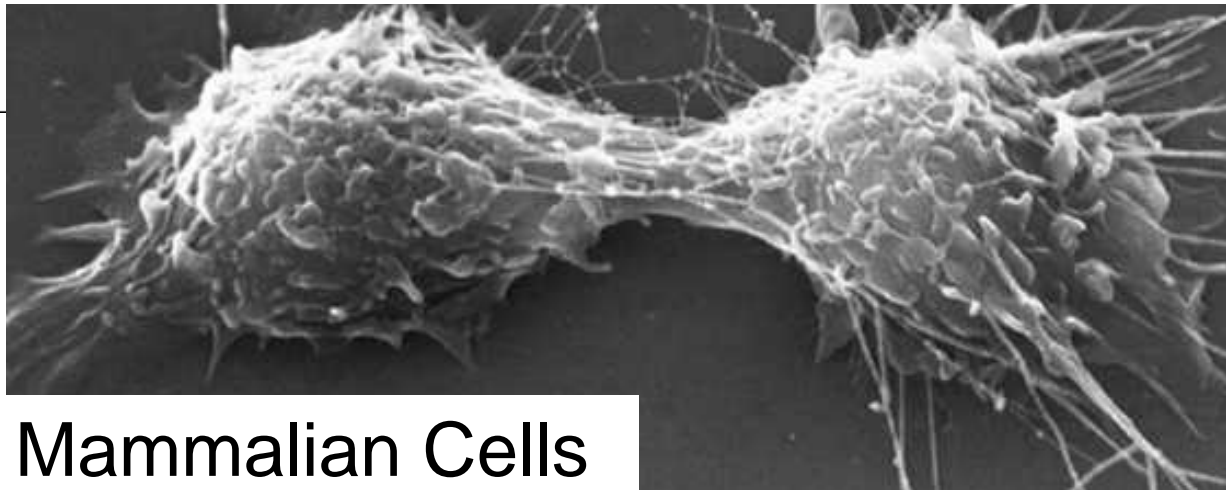
Fission Yeast



Budding Yeast



Is the control mechanism universal?



Mammalian Cells

Gene conversion table

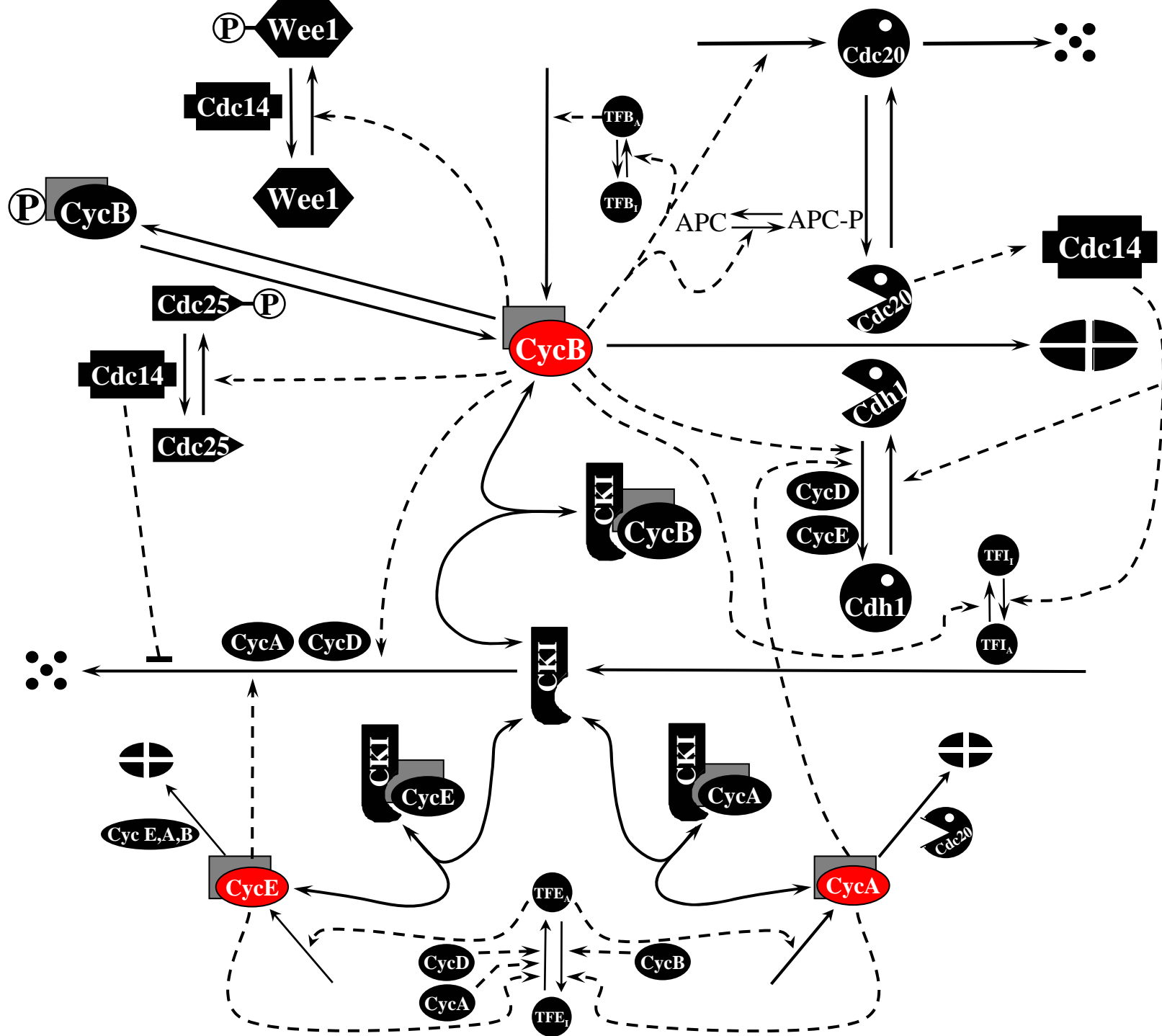
Frog egg	Budding Y	Fission Y	Mammalian
Cdc2	Cdc2	Cdc28	Cdk1, Cdk2
CycB	Clb2	Cdc13	CycB
CycA	Clb5	Cig2	CycA
CycE	Cln2	-	CycE

Is the control mechanism governed by the same dynamical principles in all eukaryotes?

Fizzy	Cdc20	Slp1	Cdc20
?	Cdc14	Clp1/Flp1	Cdc14
Mcm	Mcm1	-	Mcm
E2F	Swi4/Swi6	Cdc10	E2F
-	Swi5	-	-
APC	APC	APC	APC

Thesis 1.

The wiring diagram is (essentially) universal;
the parameter values vary from organism to
organism.



18 algebraic equations

$$\text{Cdc14}=\text{Cdc20A}$$

$$\text{Vdb}=\text{kdbp}+\text{kdbpp}*\text{Cdh1}+\text{kdbppp}*\text{Cdc20A}$$

$$\text{Wee1}=\text{GK}(\text{kawEEP}+\text{kawEpp}*\text{Cdc14},\text{kiwee}*\text{actMPF},\text{Jawee},\text{Jiwee})$$

$$\text{Cdc25}=(\text{GK}(\text{ka25}*\text{actMPF},\text{ki25p}+\text{ki25pp}*\text{Cdc14},\text{Ja25},\text{Ji25}))$$

$$\text{Vdi}=(\text{kdiP}+\text{kdiPP}*\text{actCycA}+\text{kdiPPP}*\text{actMPF}+\text{kdiPPPP}*\text{actCycE}+\text{kdiPPPPP}*\text{SK}^m)/(1.0+\text{k14di}*\text{Cdc14})$$

$$\text{TriA}=\text{CycA}-\text{actCycA}$$

$$\text{freeCKI}=\text{CKI}-\text{TriB}-\text{TriA}-\text{TriE}$$

$$\text{Vde}=(\text{kdep}+\text{kdepp}*\text{actCycE}+\text{kdeppp}*\text{actCycA}+\text{kdepppp}*\text{actMPF})$$

$$\text{TFI}=\text{GK}(\text{kafi}*\text{Cdc14},\text{kifip}+\text{kifipp}*\text{actMPF},\text{Jafi},\text{Jifi})$$

$$\text{Vsb}=\text{ksbp}+\text{ksbpp}*\text{TFB}$$

$$\text{Vda}=\text{kdap}+\text{kdapp}*\text{Cdc20A}+\text{kdappp}*\text{Cdc20T}$$

$$\text{TFE}=\text{GK}(\text{Vatf},\text{kitfp}+\text{kitfpp}*\text{actMPF}+\text{kitfppp}*\text{actCycA},\text{Jatf},\text{Jitf})$$

$$\text{TFB}=\text{GK}(\text{kafb}*\text{actMPF},\text{kifb},\text{Jafb},\text{Jifb})$$

$$\text{Vwee}=\text{kweep}+\text{kweEpp}*\text{Wee1}$$

$$\text{V25}=\text{k25p}+\text{k25pp}*\text{Cdc25}$$

$$\text{TriE}=\text{CycE}-\text{actCycE}$$

$$\text{Vsi}=\text{ksip}+\text{ksipp}*\text{TFI}$$

$$\text{Vatf}=\text{katfp}+\text{katfpp}*\text{actCycA}+\text{katfppp}*\text{actCycE}+\text{katfpppp}*\text{SK}^m$$

13 differential equations

$$d\text{actCycA}/dt=((\text{ksap}+\text{ksapp}*\text{TFE})^m+\text{Vdi}*\text{TriA}+\text{kdia}*\text{TriA}) - ((\text{Vda}+\text{kasa}*\text{freeCKI})^m*\text{actCycA})$$

$$d\text{actMPF}/dt=(\text{Vsb}^m+\text{V25}*(\text{CycB}-\text{TriB}-\text{actMPF})+(\text{kdiB}+\text{Vdi})*(\text{CycB}-\text{preMPF}-\text{actMPF})) - ((\text{Vdb}+\text{Vwee}+\text{kasb}*\text{freeCKI})^m*\text{actMPF})$$

$$d\text{Cdc20A}/dt=(\text{ka20}*\text{IEP}*(\text{Cdc20T}-\text{Cdc20A})/(\text{Ja20}+\text{Cdc20T}-\text{Cdc20A})) - ((\text{ki20}/(\text{Ji20}+\text{Cdc20A})+\text{kd20})^m*\text{Cdc20A})$$

$$d\text{Cdc20T}/dt=(\text{ks20p}+\text{ks20pp}*\text{actMPF}^n/(\text{J20}^n+\text{actMPF}^n)) - (\text{kd20}*\text{Cdc20T})$$

$$d\text{Cdh1}/dt=((\text{kah1p}+\text{kah1pp}*\text{Cdc14})^m*(1.0-\text{Cdh1})/(\text{Jah1}+1.0-\text{Cdh1})) - (((\text{kih1p}+\text{kih1pp}*\text{actCycA}+\text{kih1ppp}*\text{actMPF}+\text{kih1pppp}*\text{actCycE}+\text{kih1ppppp}*\text{SK}^m)/(\text{Jih1}+\text{Cdh1}))^m*\text{Cdh1})$$

$$d\text{CKI}/dt=(\text{Vsi}) - (\text{Vdi}*\text{CKI})$$

$$d\text{CycE}/dt=((\text{ksep}+\text{ksepp}*\text{TFE})^m) - (\text{Vde}*\text{CycE})$$

$$d\text{actCycE}/dt=((\text{ksep}+\text{ksepp}*\text{TFE})^m) + ((\text{kdie}+\text{Vdi})*(\text{CycE}-\text{actCycE})) - ((\text{kase}*\text{freeCKI}+\text{Vde})^m*\text{actCycE})$$

$$d\text{CycB}/dt=(\text{Vsb}^m) - (\text{Vdb}*\text{CycB})$$

$$d\text{CycA}/dt=((\text{ksap}+\text{ksapp}*\text{TFE})^m) - (\text{Vda}*\text{CycA})$$

$$d\text{IEP}/dt=(\text{kaie}*\text{actMPF}*(1.0-\text{IEP})/(\text{Jaie}+1.0-\text{IEP})) - ((\text{kiie}/(\text{Jiie}+\text{IEP}))^m*\text{IEP})$$

$$d\text{preMPF}/dt=(\text{Vwee}*(\text{CycB}-\text{preMPF})) - ((\text{V25}+\text{Vdb})^m*\text{preMPF})$$

$$d\text{TriB}/dt=(\text{kasb}*(\text{CycB}-\text{TriB})^m*\text{freeCKI}) - ((\text{kdiB}+\text{Vdb}+\text{Vdi})^m*\text{TriB})$$

86 parameters

kasb
kase
katfp
katfpp
katfppp
katfpppp
kawEEP
kawEpp
kd20
kdap
kdapp
kdappp
kdbp
kdbpp
kdbppp
kdbpppp
kdep

etc.

Parameter Tables

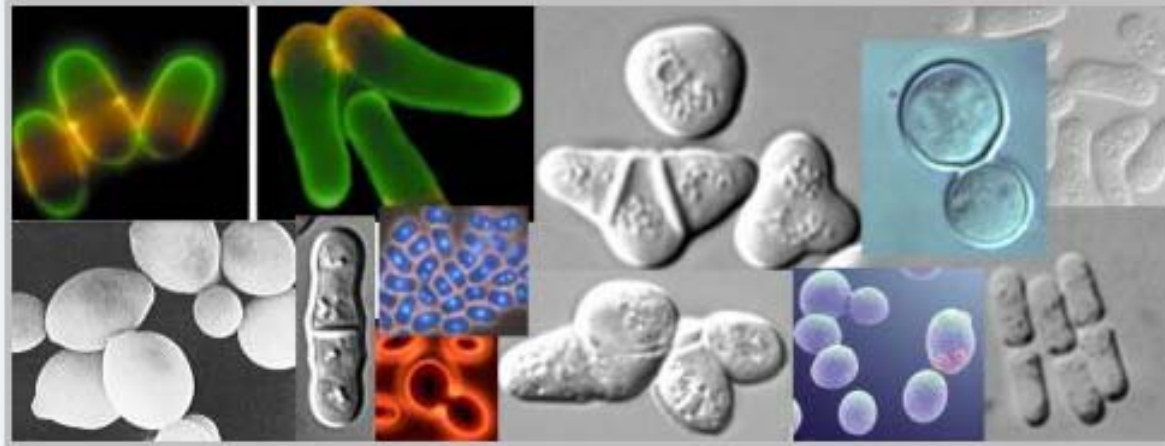
	BUDDING	MAMMALIAN	POMBE	MORPHO	FROG
J20	100	100	0.05	100	0
Ja20	10	0.005	0.001	10	0.1
Ja25	0	0	0.01	0.1	0.1
Jafb	0.1	0.1	0	0.1	0
Jafi	10	0	0	10	0
Jah1	0.03	0.01	0.01	0.03	0
Jaie	0.1	0.01	0.001	0.1	0.01
Jatf	0.01	0.01	0.01	0.01	0
Jawee	0	0	0.01	0.05	0.3
Ji20	10	0.005	0.001	10	0.1
Ji25	0	0	0.01	0.1	0.1
Jifb	0.1	0.1	0	0.1	0
Jifi	10	0	0	10	0
Jih1	0.03	0.01	0.01	0.03	0
Jiie	0.1	0.01	0.001	0.1	0.01
Jitf	0.01	0.01	0.01	0.01	0
Jiwee	0	0	0.01	0.05	0.3
k14di	12	0	0	12	0
k25p	0	0	0.001	0.05	0.1
k25pp	0	0	1	0.5	1.9
ka20	1	0.5	0.2	1	0.1
ka25	0	0	1	1	1
kafb	1	1	0	1	0
kafi	6	0	0	6	0
kah1p	0.01	0.75	5	0.01	0
kah1pp	0.8	14	50	0.8	0
kaie	0.1	0.07	0.2	0.1	2
kasa	50	100	500	50	0

	BUDDING	MAMMALIAN	POMBE	MORPHO	FROG
kasb	65	0	1000	65	0
kase	0	100	0	0	0
katfp	0	0	1.5	0	0
katfpp	0.76	0.3	0	0.76	0
katfppp	0.76	0.5	0	0.76	0
katfpppp	3.8	0.33	0	3.8	0
kawee	0	0	0.25	0.3	0.1
kaweep	0	0	0.25	0	0
kd20	0.05	0.15	0.1	0.05	1
kdap	0.01	0.002	0.01	0.01	0
kdapp	0.16	2	2	0.16	0
kdappp	0	0	0.02	0	0
kdbp	0.003	0.005	0.02	0.003	0.015
kdbpp	0.4	2	0.75	0.4	0
kdbppp	0.15	0.1	1.5	0.15	0.985
kdep	0.12	0.01	0	0.12	0
kdepp	0	0.1	0	0	0
kdeppp	0	1	0	0	0
kdepppp	0	1	0	0	0
kdia	0.06	1	1	0.06	0
kdib	0.05	0	1	0.05	0
kdie	0	1	0	0	0
kdip	0.02	1	0.1	0.02	0
kdipp	0.2	5	2	0.2	0
kdippp	0.9	10	100	0.9	0
kdipppp	0.12	5	0	0.12	0
kdippppp	0.66	0	1	0.66	0
ki20	0.05	0.25	0.05	0.05	0.095

	BUDDING	MAMMALIAN	POMBE	MORPHO	FROG
ki25p	0	0	0.25	0.3	0.125
ki25pp	0	0	0.25	0	0
kifb	0.15	0.1	0	0.15	0
kifip	0.008	0	0	0.008	0
kifipp	0.05	0	0	0.05	0
kih1p	0.001	0	1	0.001	0
kih1pp	0.64	1.2	40	0.64	0
kih1ppp	0.1	4	40	0.1	0
kih1pppp	0.032	0	0	0.032	0
kih1ppppp	0.01	0	40	0.01	0
kiie	0.15	0.18	0.08	0.15	0.15
kiitfp	0.6	0.25	1	0.6	0
kiitfpp	8	0.1	0	8	0
kiitfppp	0	0.1	10	0	0
kiwee	0	0	1	1	3
ks20p	0.001	0	0.005	0.001	1
ks20pp	10	15	0.1	10	0
ksap	0.0008	0	0	0.0008	0
ksapp	0.005	0.025	0.02	0.005	0
ksbp	0.004	0.01	0.02	0.004	0.1
ksbpp	0.04	0.03	0	0.04	0
ksep	0	0.008	0	0	0
ksepp	0.15	0.3	0	0.15	0
ksip	0.036	2	0.3	0.036	0
ksipp	0.24	0	0	0.24	0
kweep	0	0	0.05	0.2	0.1
kweepp	0	0	0.5	2	0.9
m	0.1	0.1	0.1	0.1	0.001
n20	1	1	4	1	0
SK	0.108	0.5	0.05	0.108	0

Red rectangle: Parameter is not used in simulations of that organism

Welcome to the Generic Cell Cycle Homepage



1 2 2 0

This is the companion website to the [paper](#):

Attila Csikasz-Nagy, Dorjsuren Battogtokh, Kathy Chen, Bela Novak & John J. Tyson
Analysis of a generic model of eukaryotic cell cycle regulation

published in [Biophysical Journal](#) (2006) 90:4361-79

© Attila Csikasz-Nagy, Kathy Chen, Jason Zwolak and John Tyson, 2006

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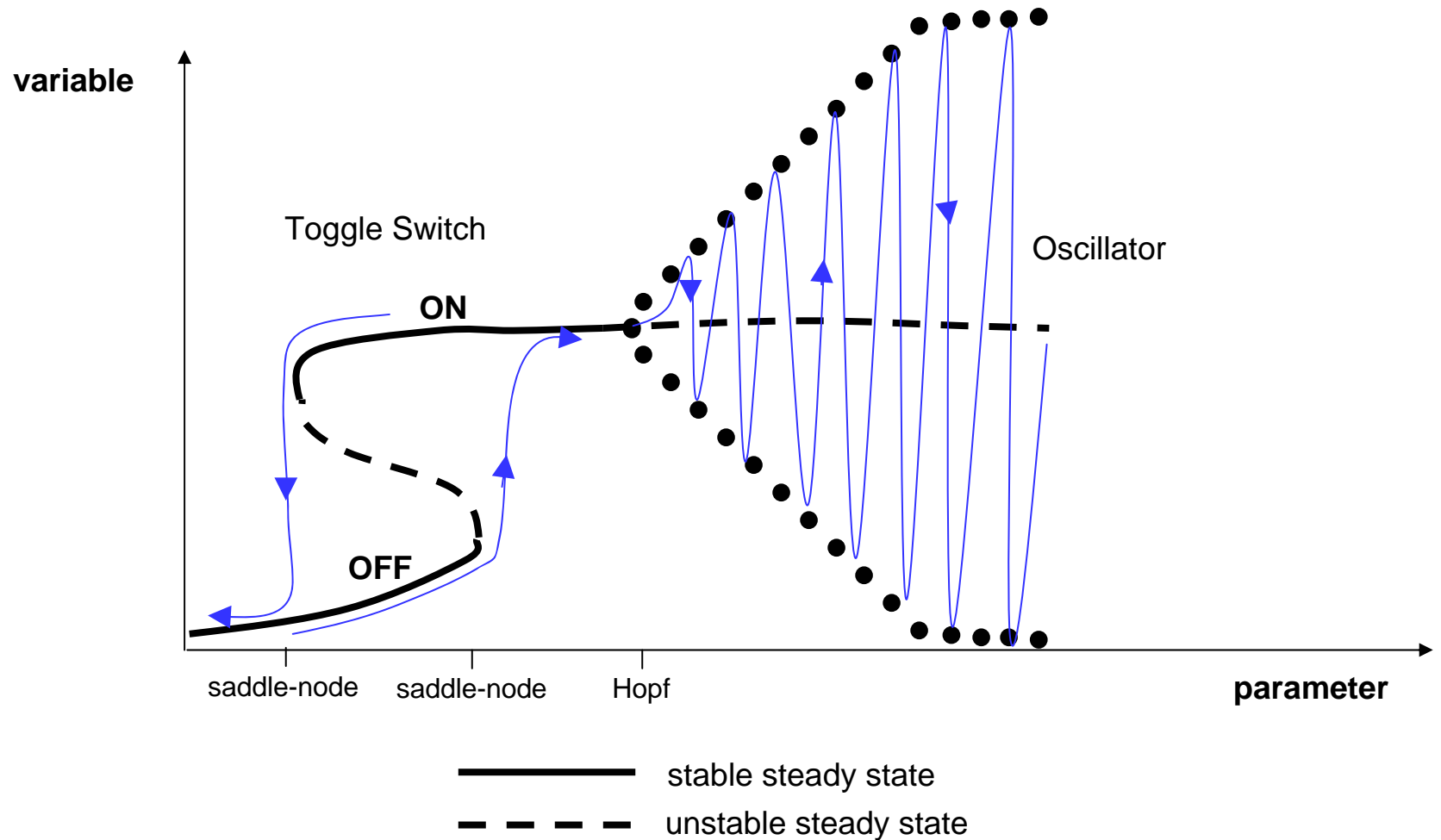
Page modified Jun 09, 2006

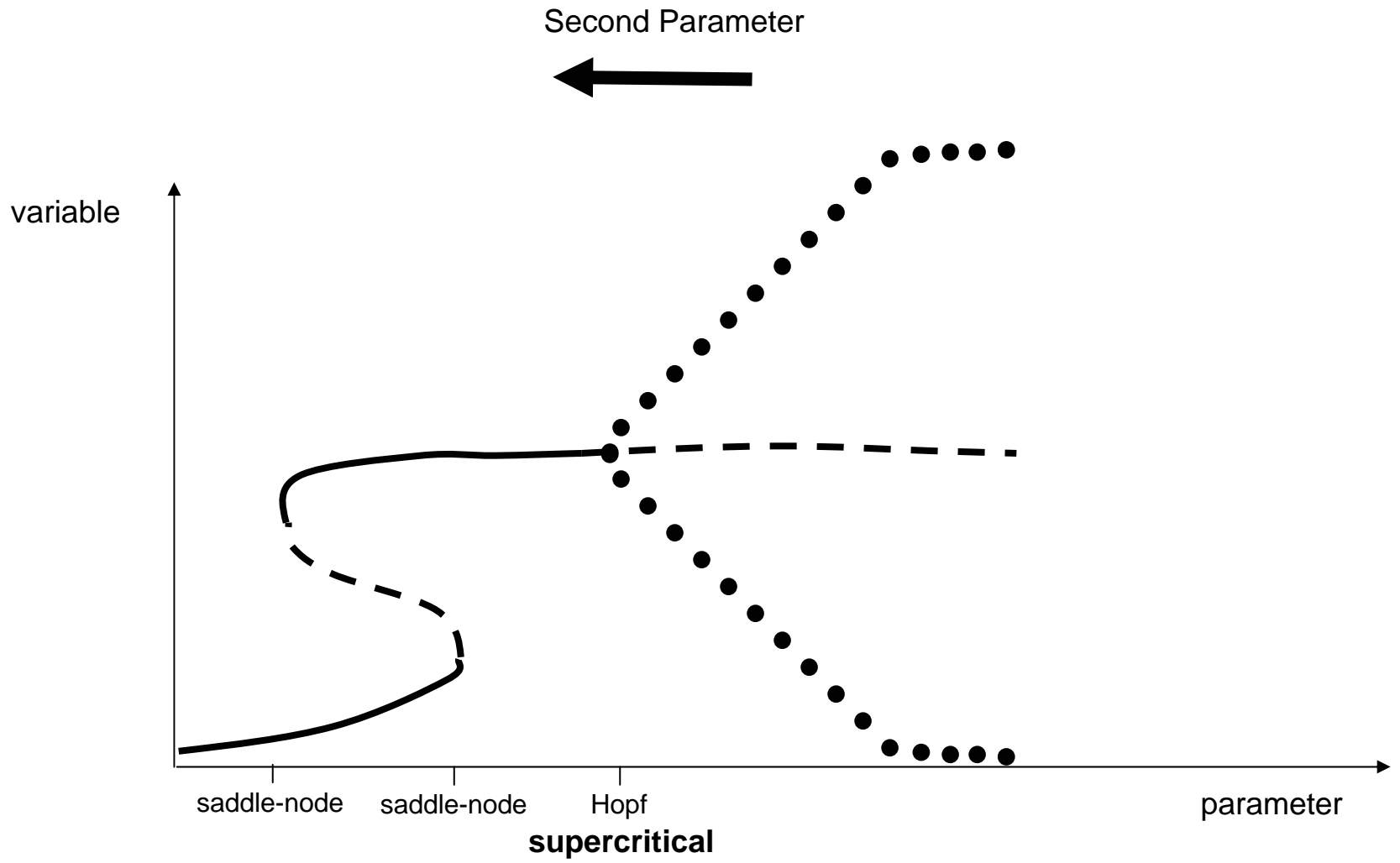
www.mpf.biol.vt.edu

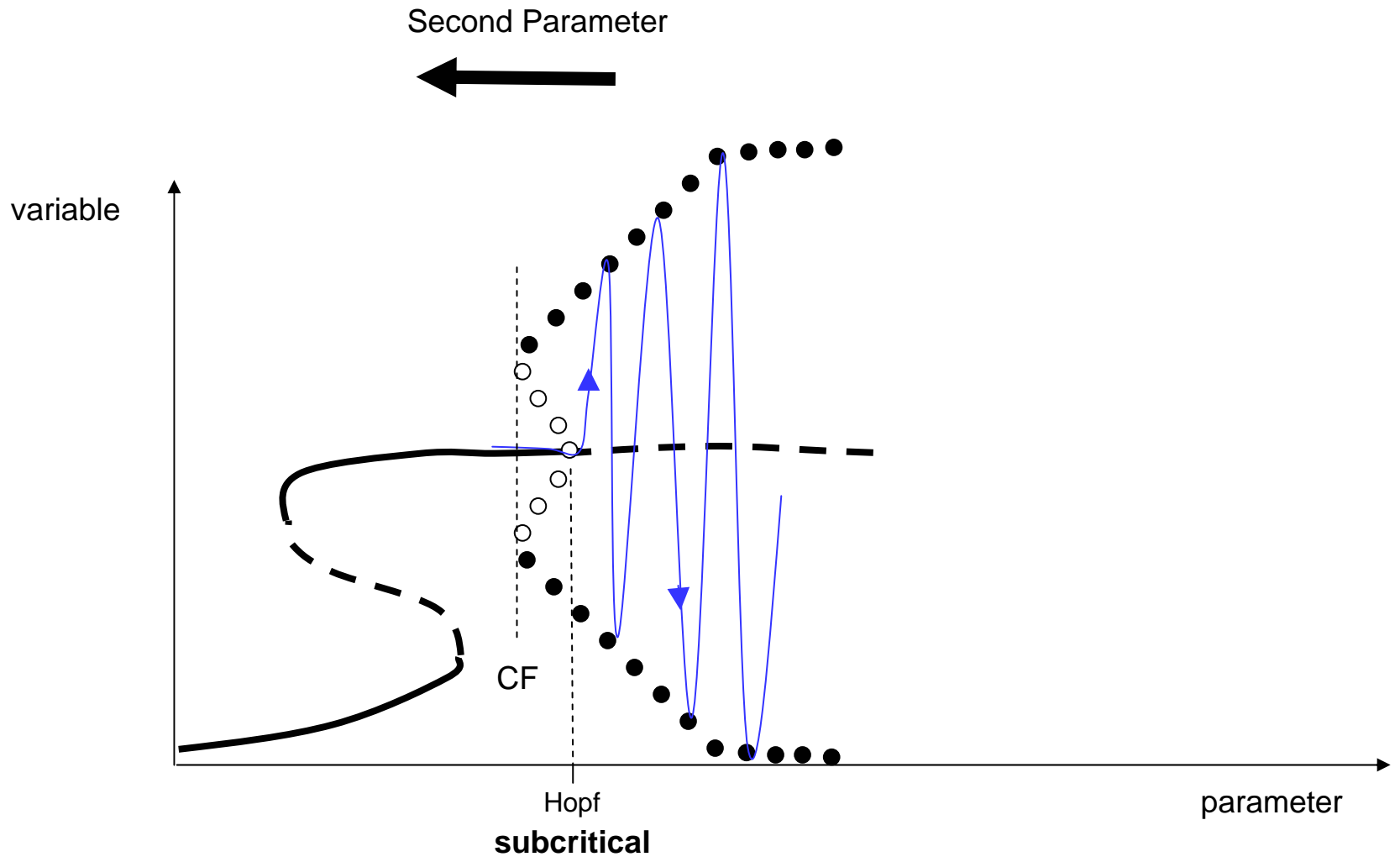
Thesis 2.

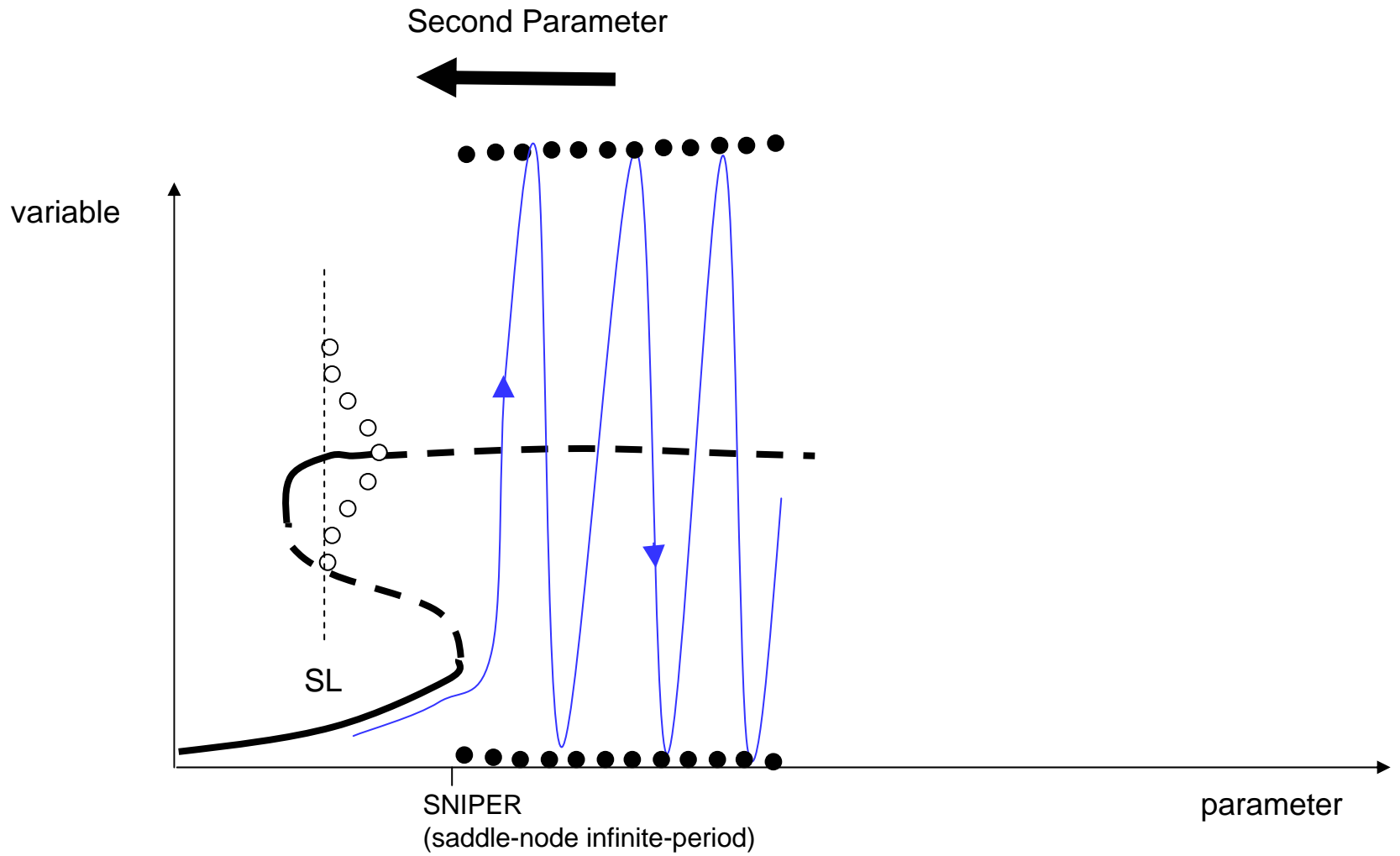
One-parameter bifurcation diagrams govern progression through the cell cycle.

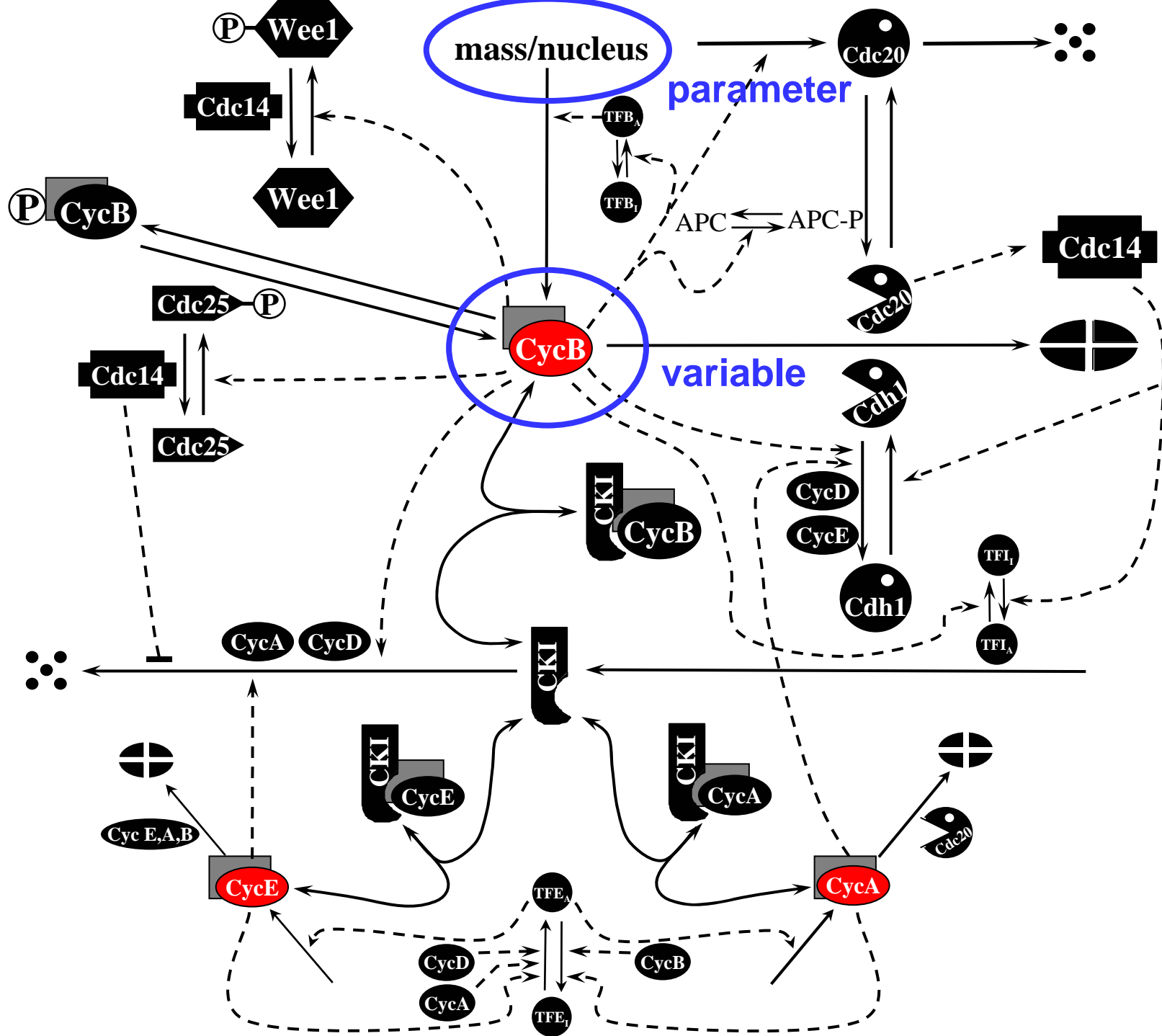
One-parameter bifurcation diagram



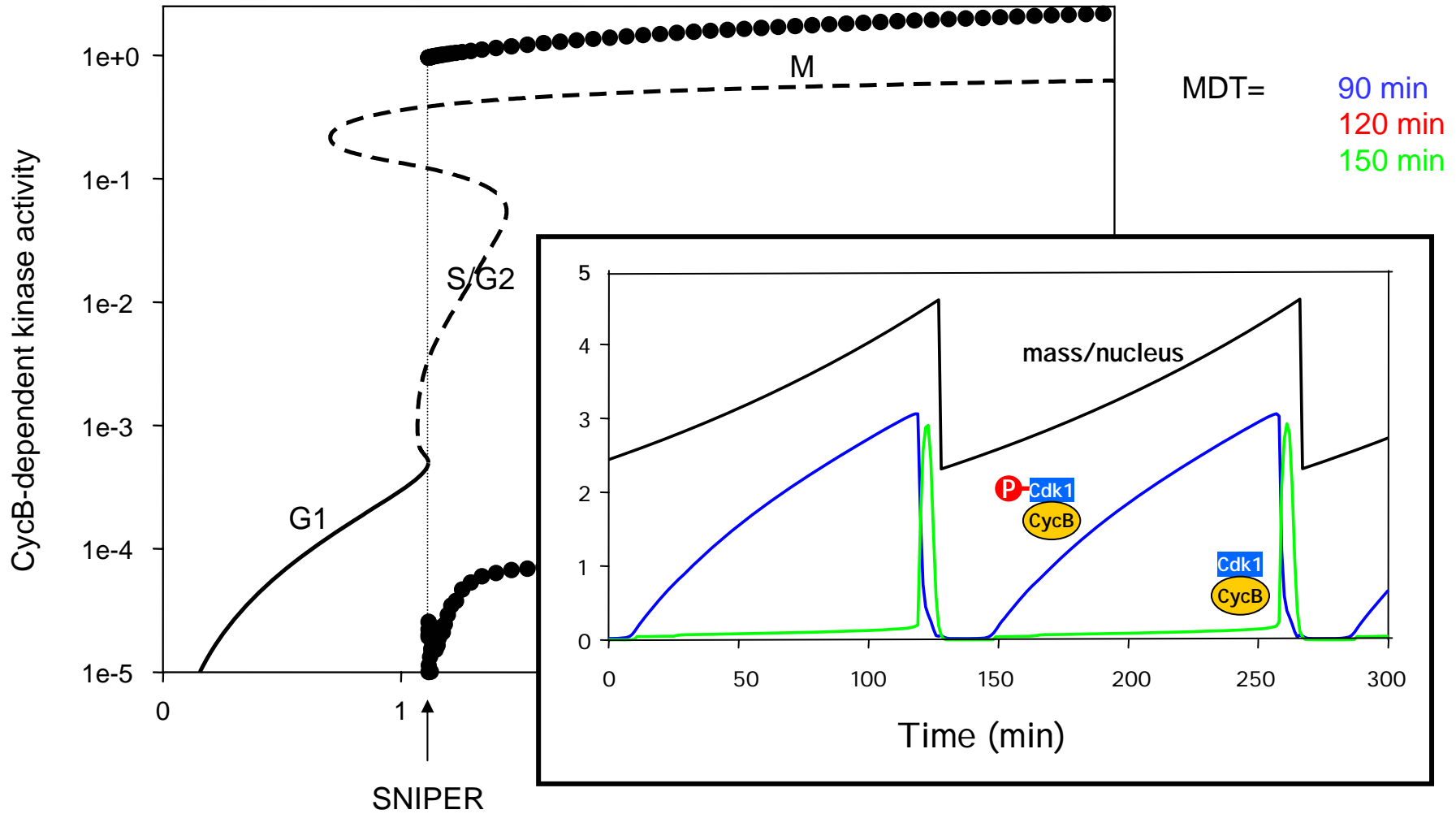




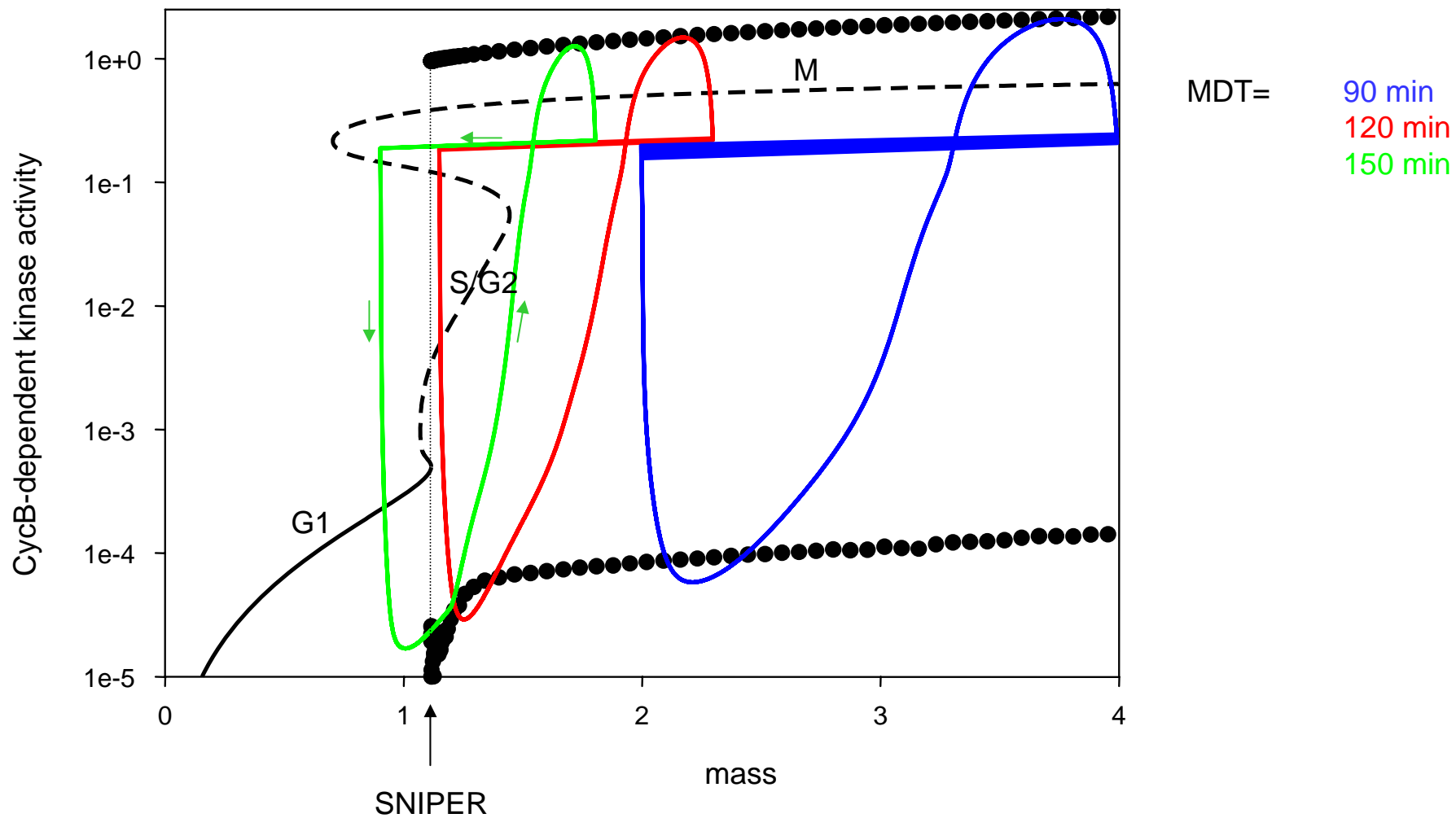


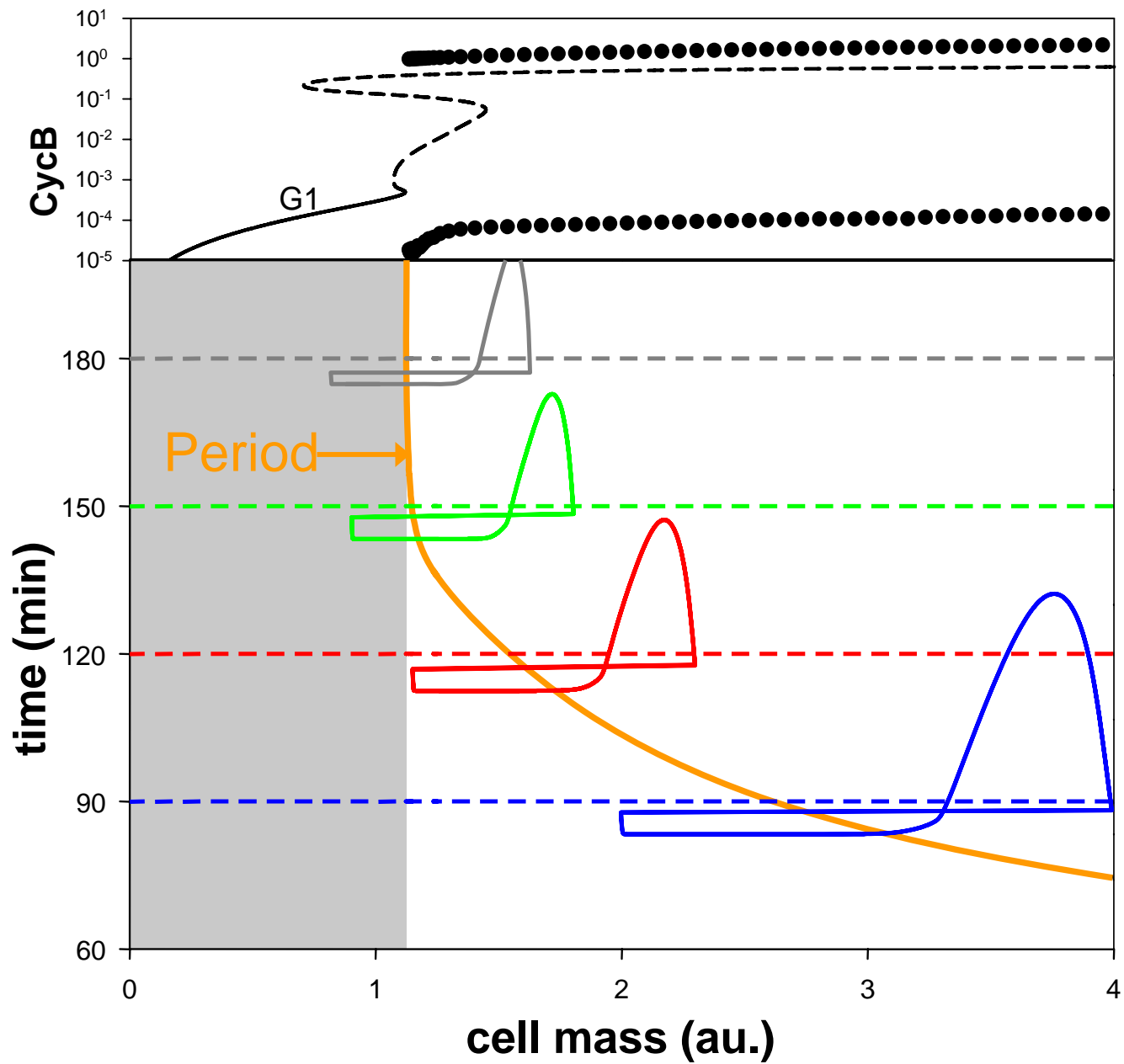


Wild type cells



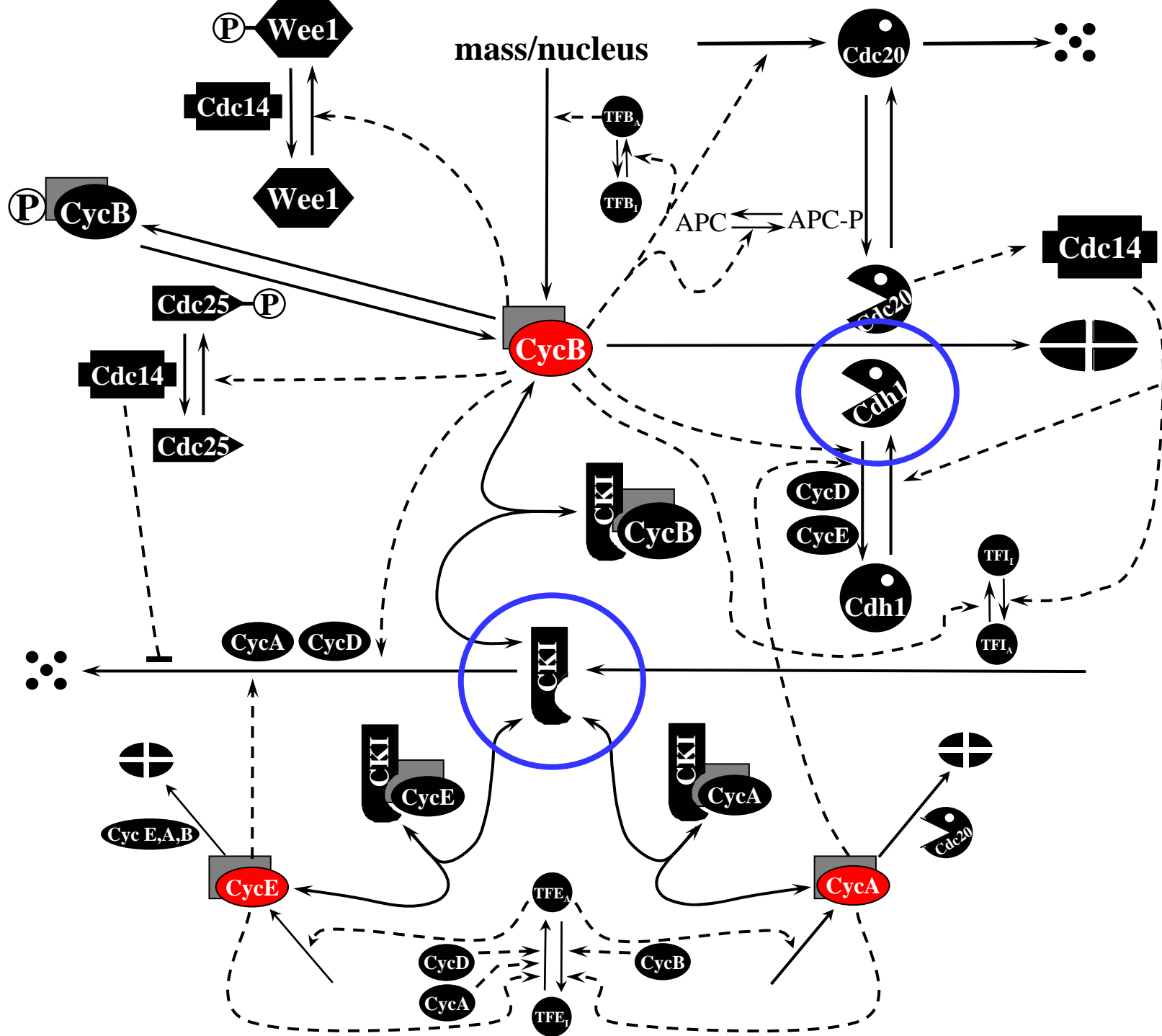
Wild type cells



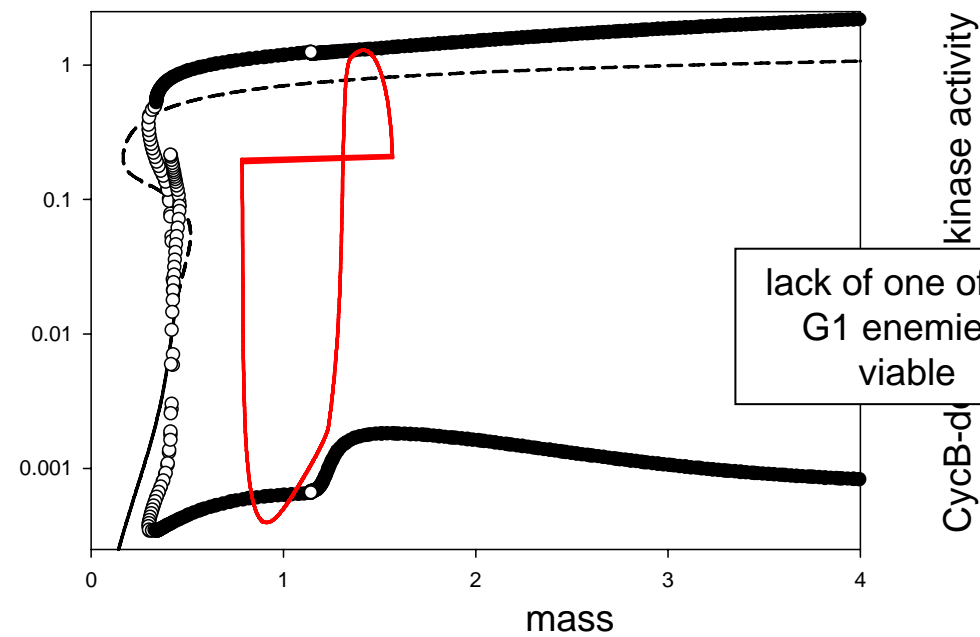


Thesis 3.

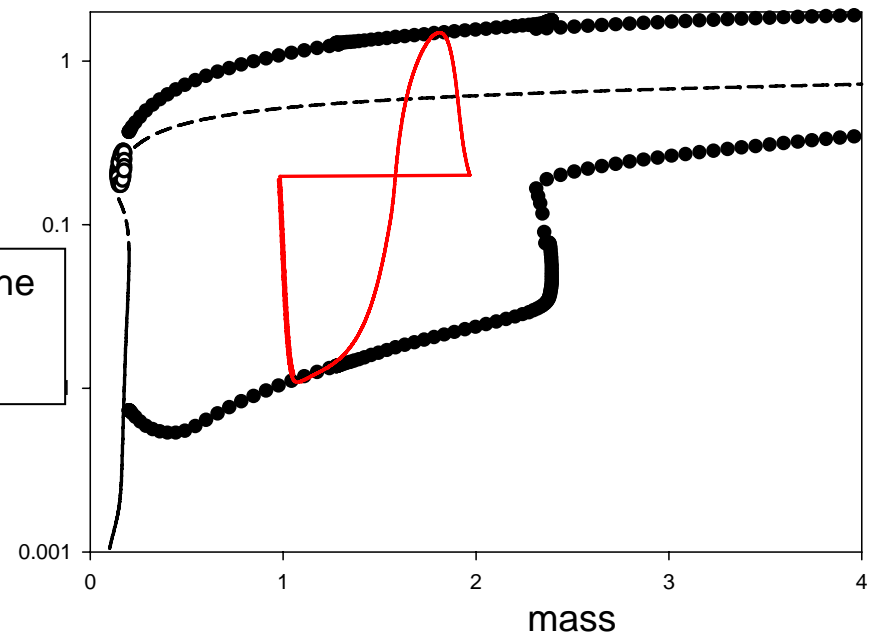
Mutant phenotypes are direct consequences of altered bifurcation diagrams.

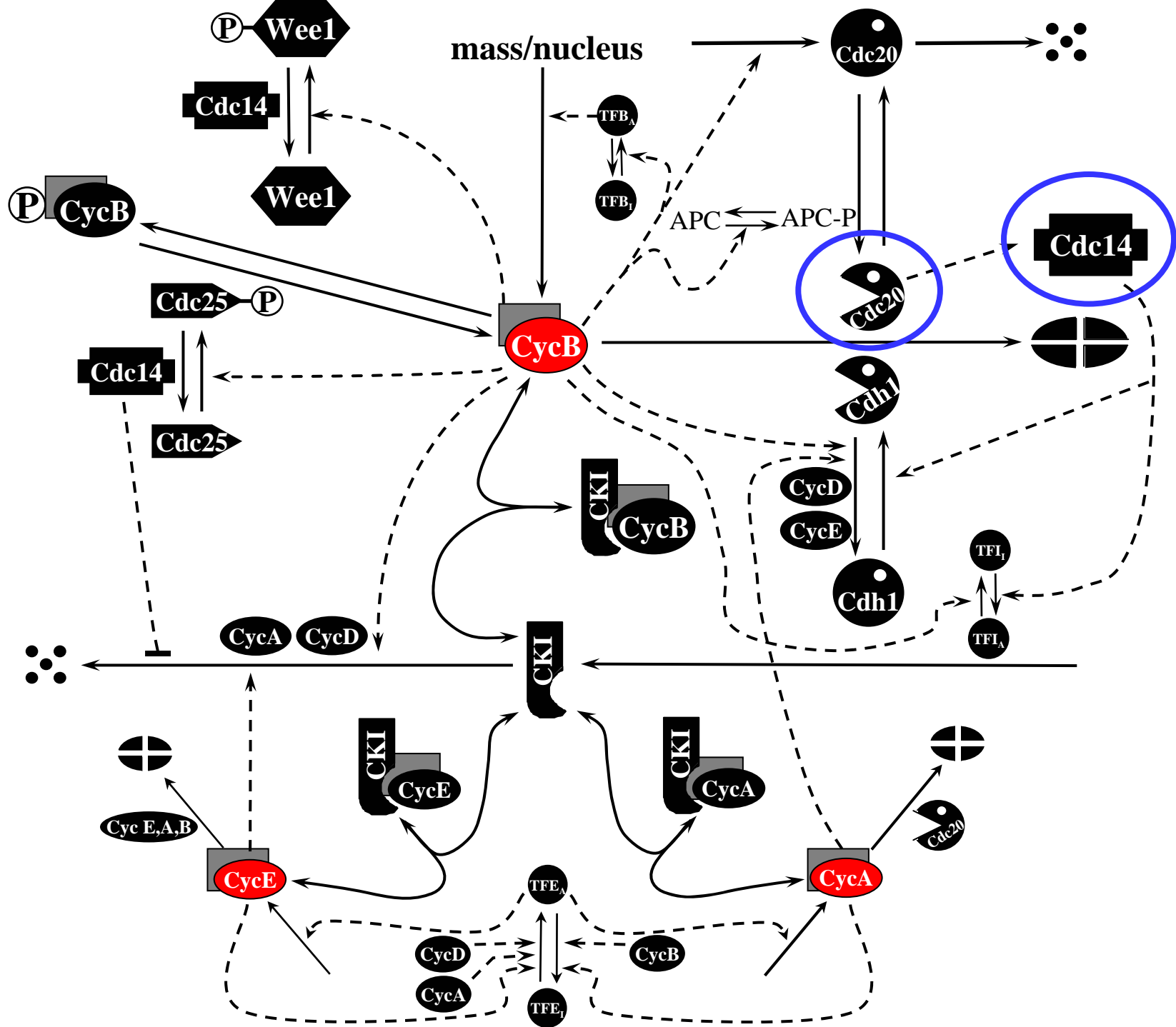


cdh1 Δ

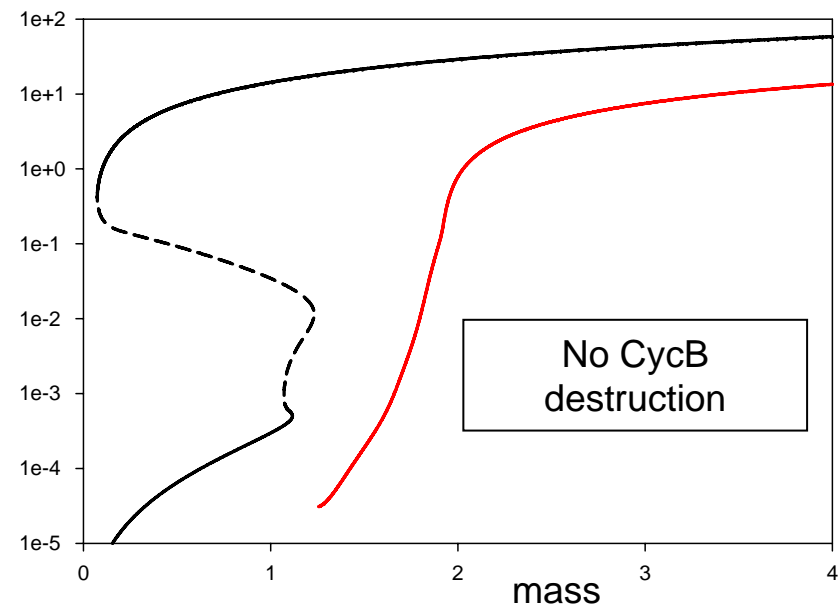


cki Δ

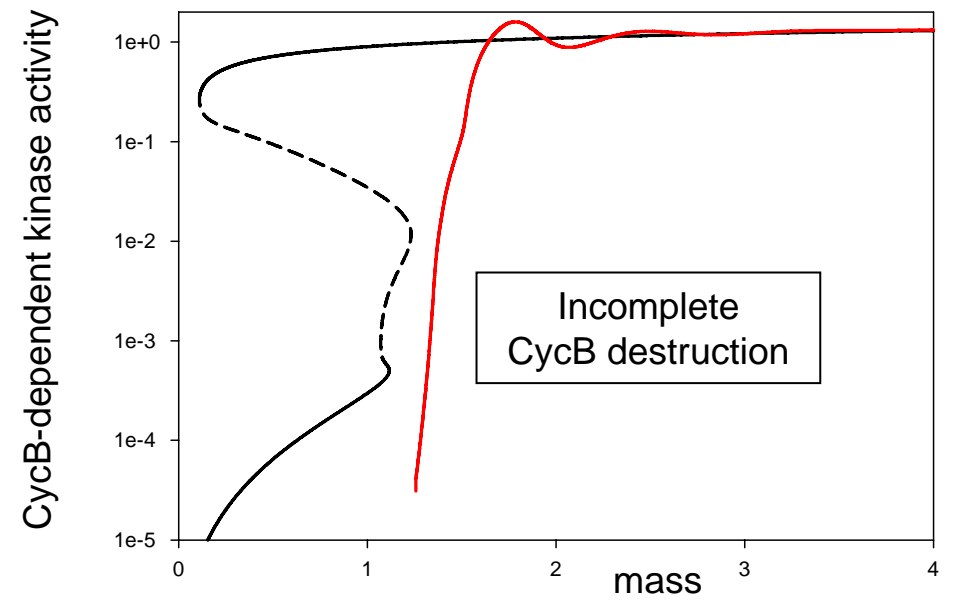




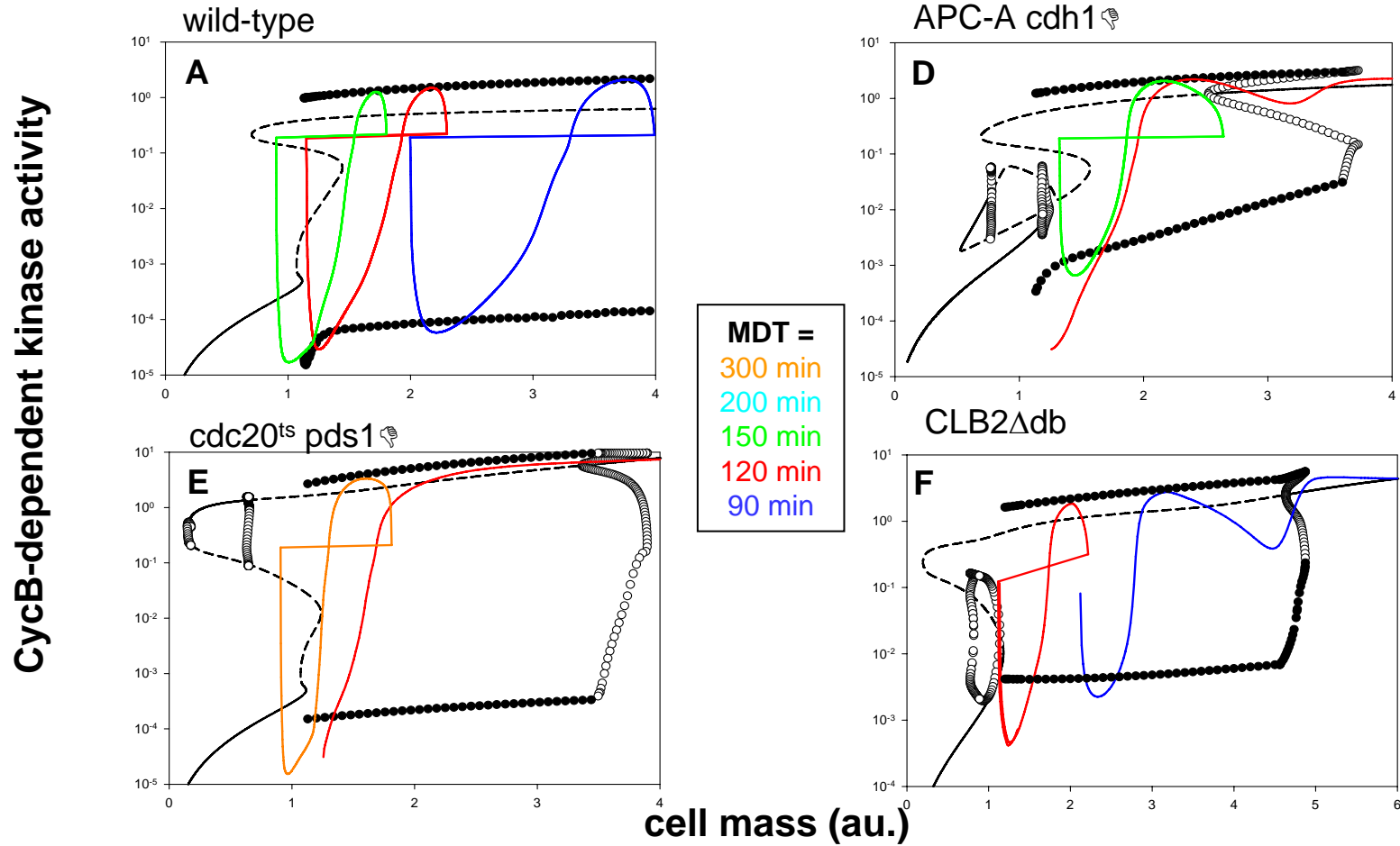
cdc20 Δ



cdc14 Δ



Defects in Exit from Mitosis

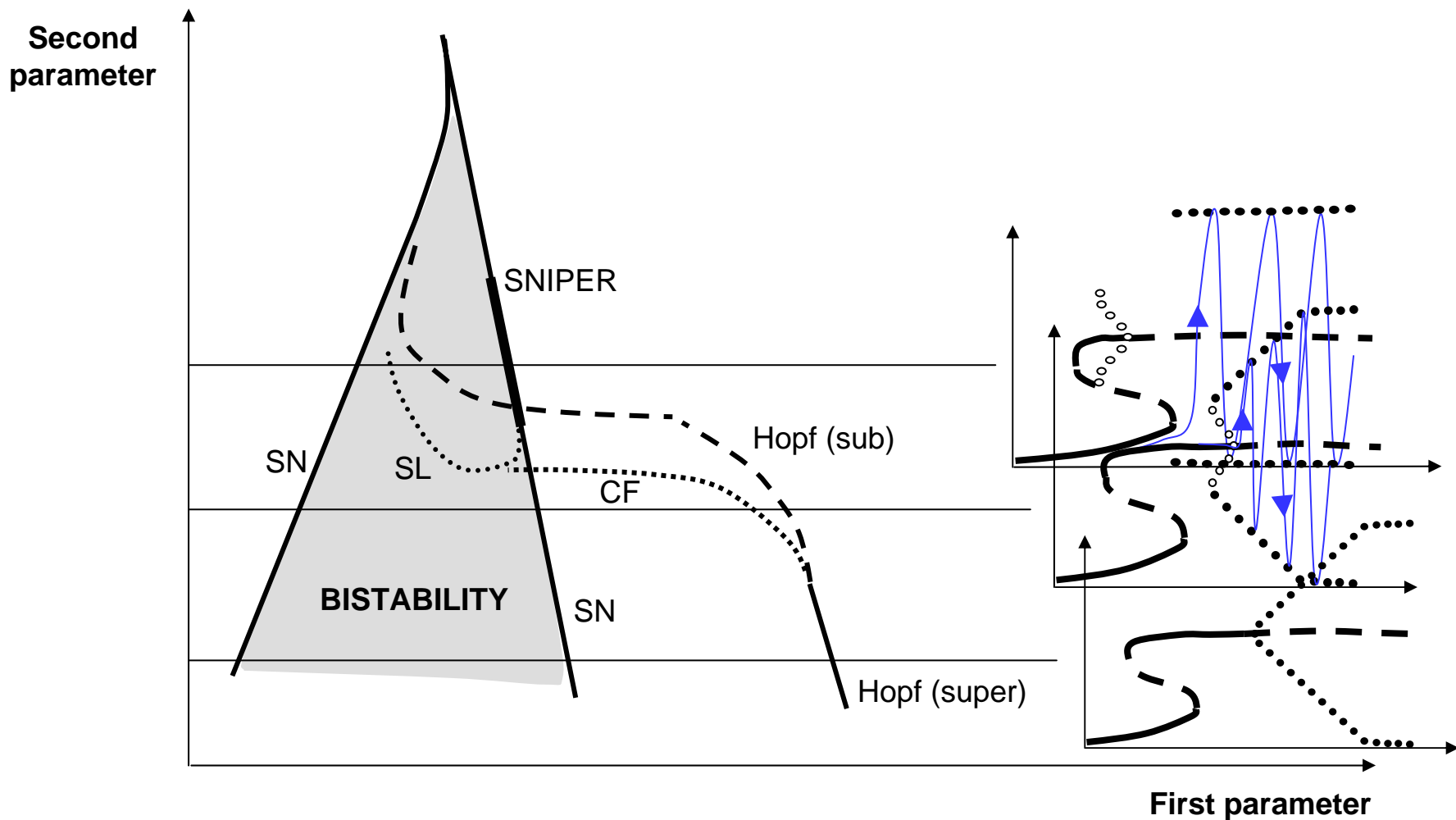


Viability depends on growth rate!

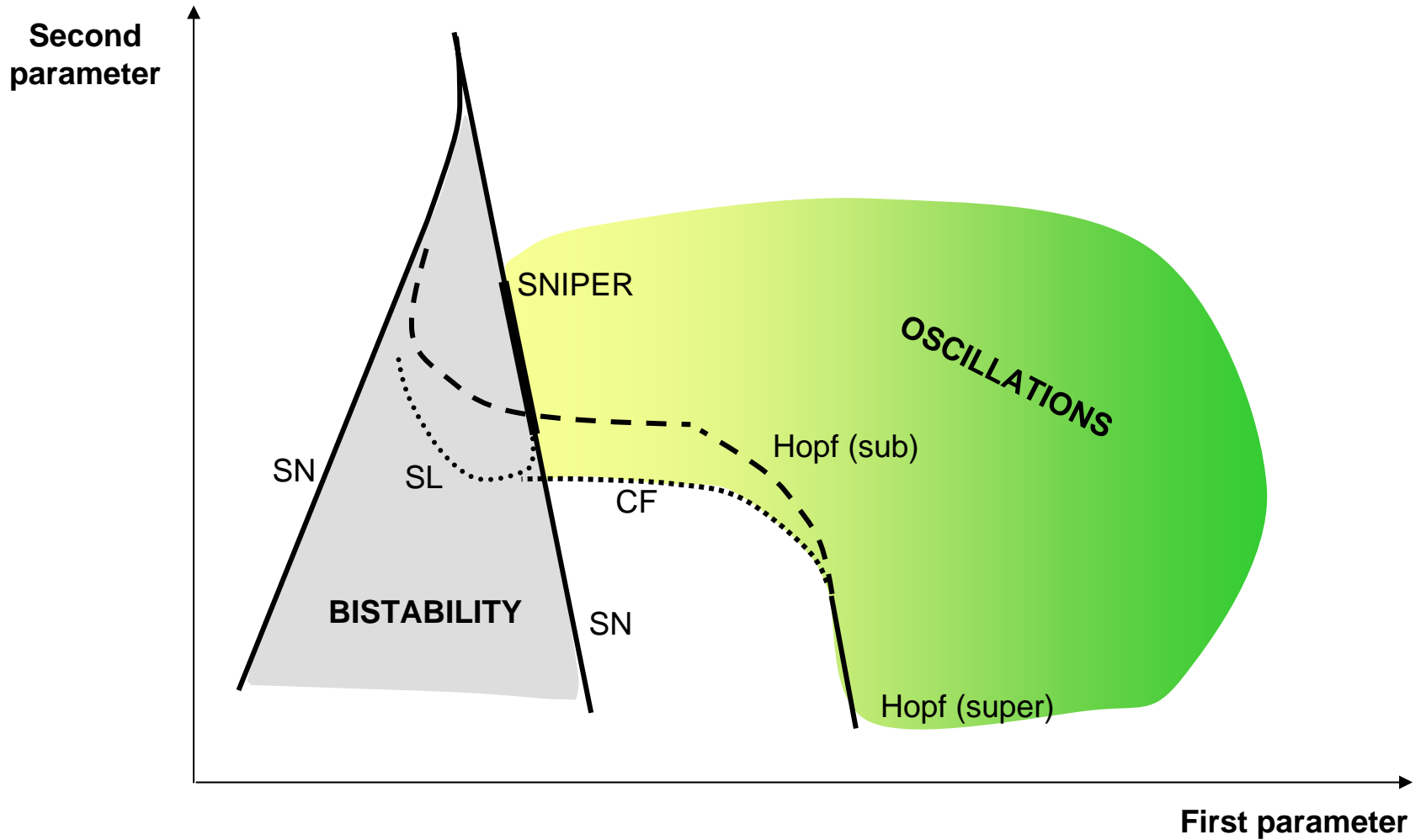
Thesis 4.

Two-parameter bifurcation diagrams
connect genetics to physiology.

Two-parameter bifurcation diagram

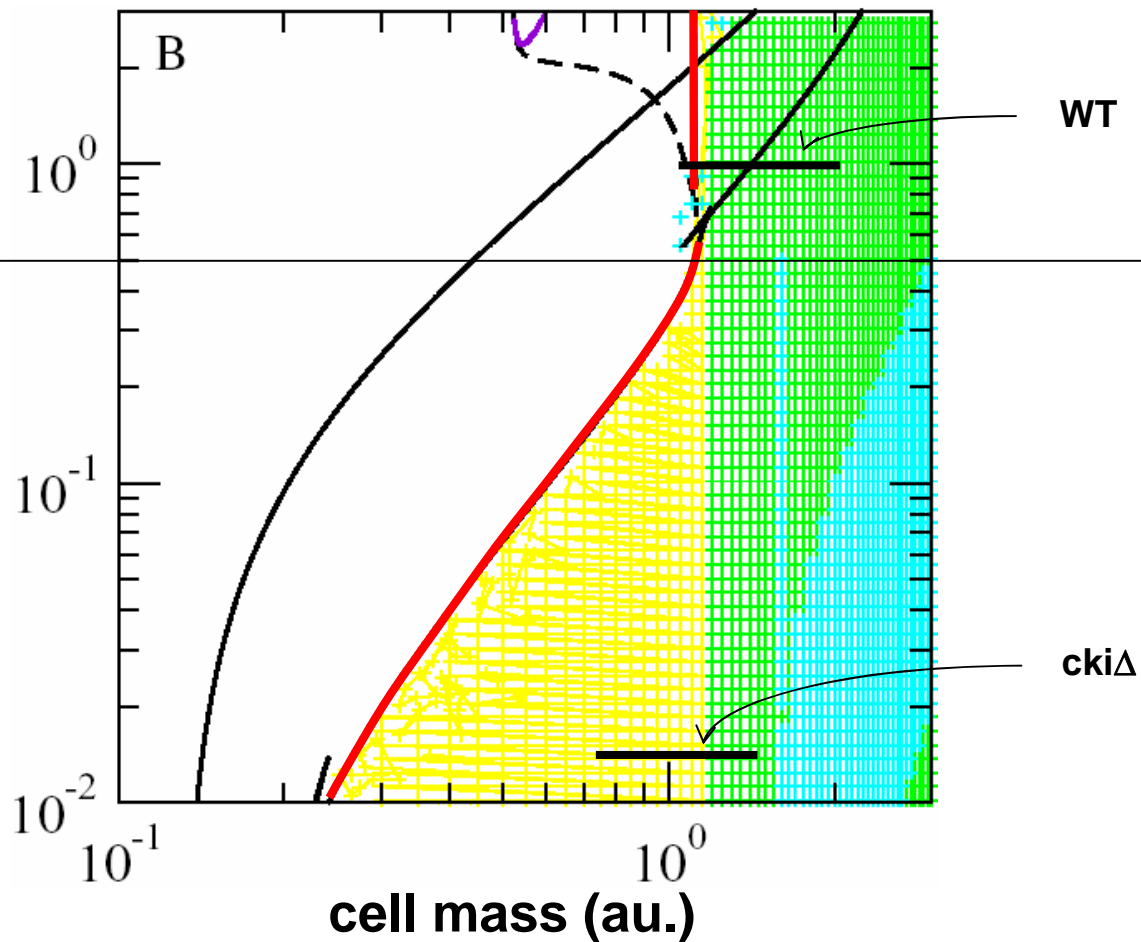


Two-parameter bifurcation diagram

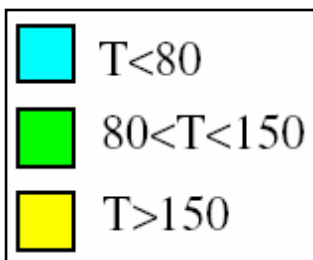


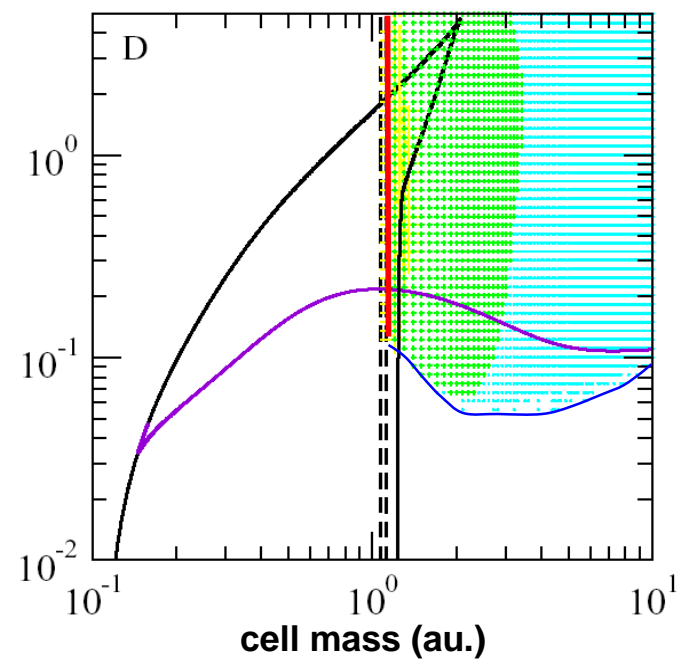
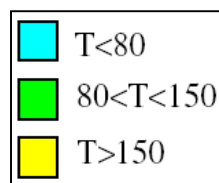
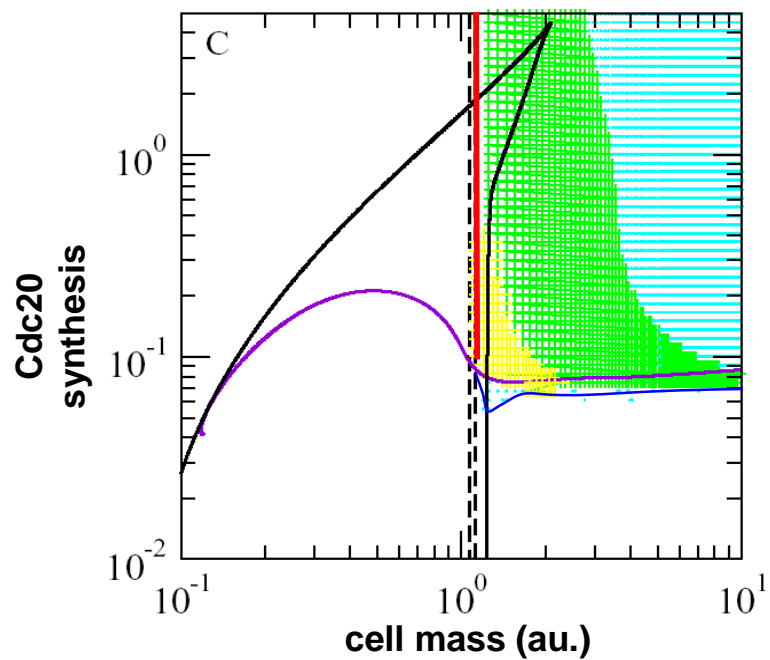
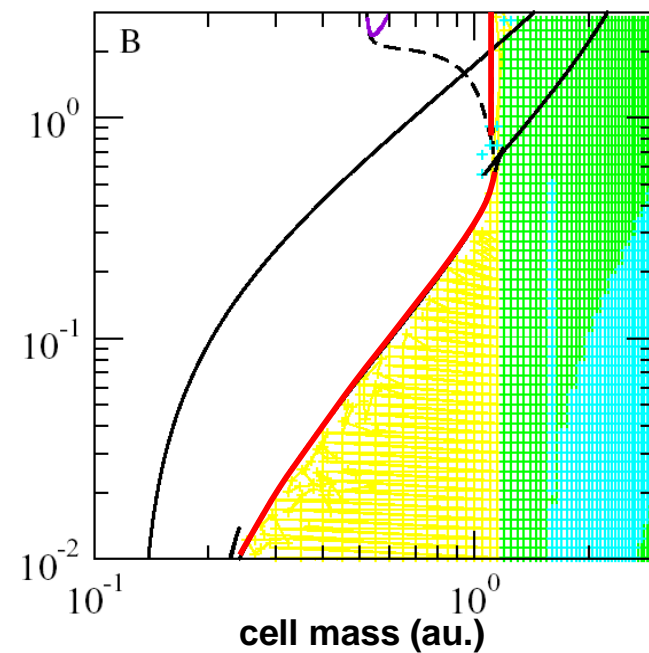
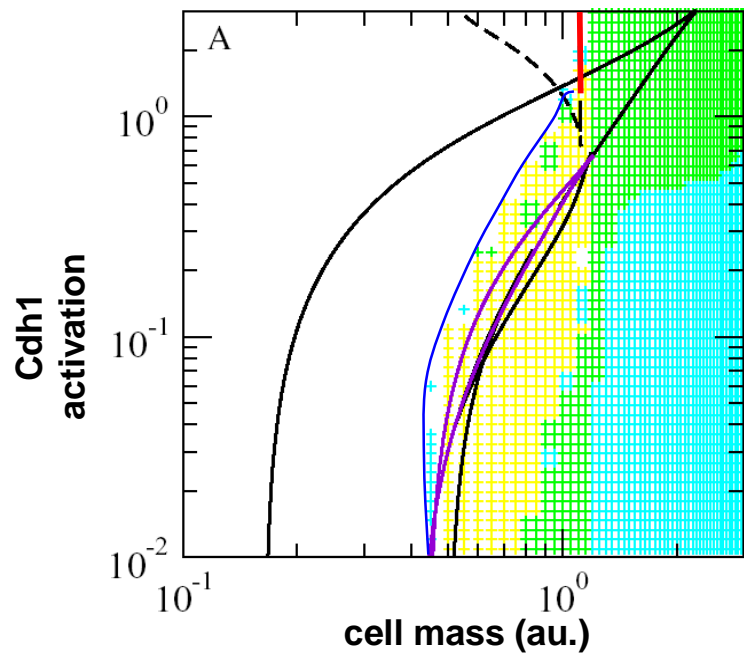
GENETICS

Cki
synthesis



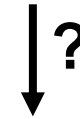
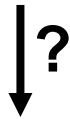
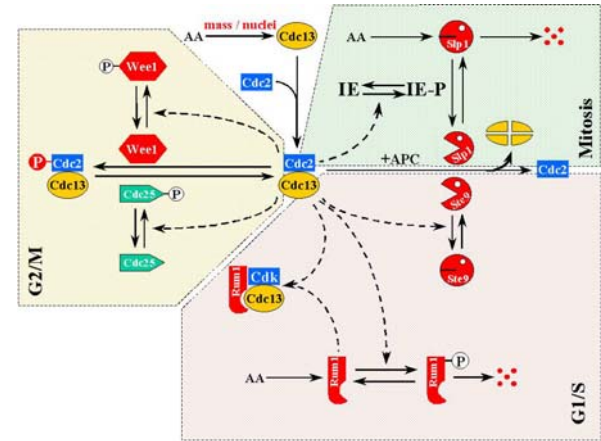
PHYSIOLOGY





The Dynamical Perspective

Molecular Mechanism



Physiological Properties



The Dynamical Perspective

Molecular Mechanism



Kinetic Equations

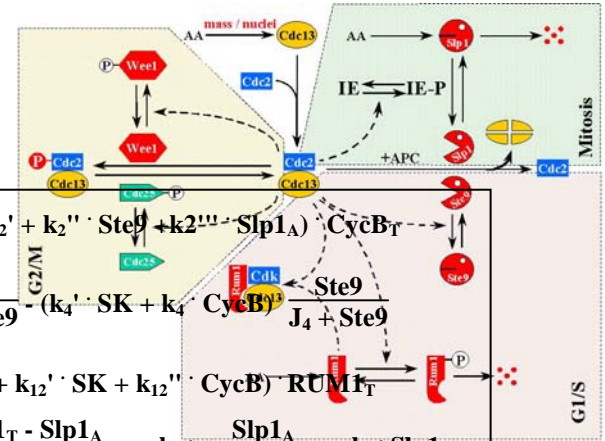
$$\frac{d \text{CycB}_T}{dt} = k_1 \cdot M - (k_2' + k_2'' \cdot \text{Ste9} + k_2''' \cdot \text{Slp1}_A) \cdot \text{CycB}_T$$

$$\frac{d \text{Ste9}}{dt} = k_3' \cdot \frac{1 - \text{Ste9}}{J_3 + 1 - \text{Ste9}} - (k_4' \cdot \text{SK} + k_4 \cdot \text{CycB}^B) \cdot \frac{\text{Ste9}}{J_4 + \text{Ste9}}$$

$$\frac{d \text{Rum1}_T}{dt} = k_{11} - (k_{12} + k_{12}' \cdot \text{SK} + k_{12}'' \cdot \text{CycB}) \cdot \text{RUM1}_T$$

$$\frac{d \text{Slp1}_A}{dt} = k_7 \cdot \text{IE} \cdot \frac{\text{Slp1}_T - \text{Slp1}_A}{J_7 + \text{Slp1}_T - \text{Slp1}_A} - k_8 \cdot \frac{\text{Slp1}_A}{J_8 + \text{Slp1}_A} - k_6 \cdot \text{Slp1}_A$$

$$\frac{dM}{dt} = \mu \cdot M$$



Physiological Properties



The Dynamical Perspective

Molecular Mechanism



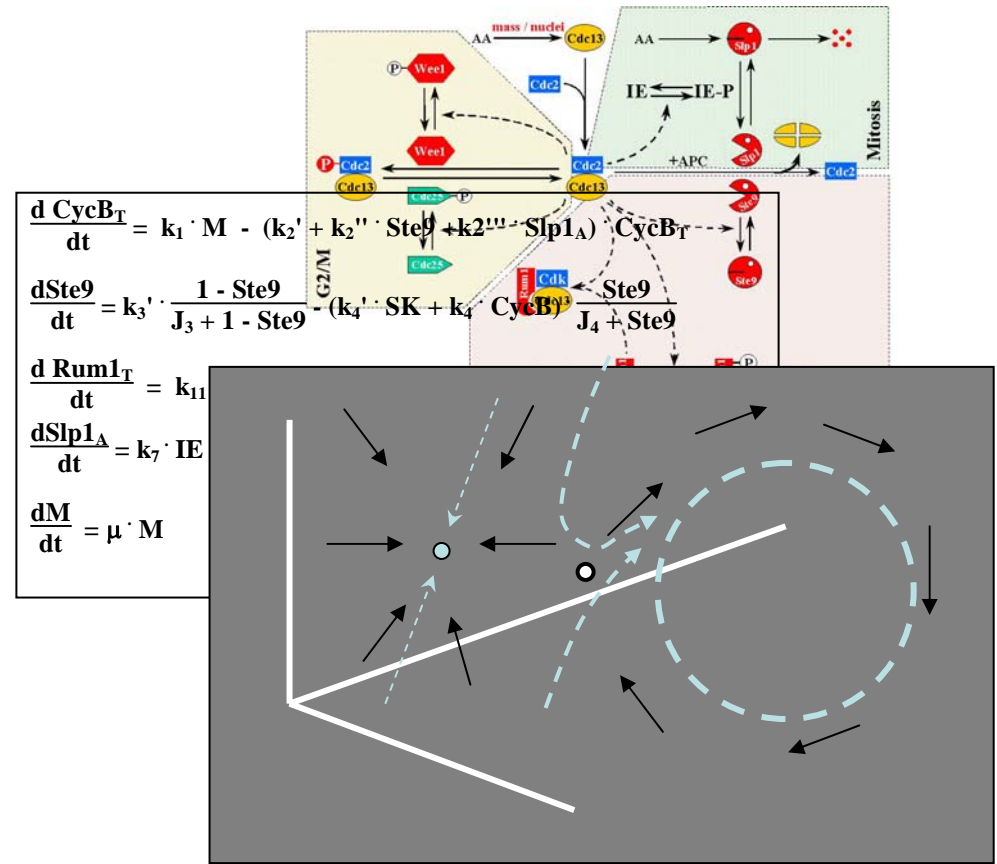
Kinetic Equations



Vector Field



Stable Attractors



Physiological Properties



The Dynamical Perspective

Molecular Mechanism



Kinetic Equations



Vector Field



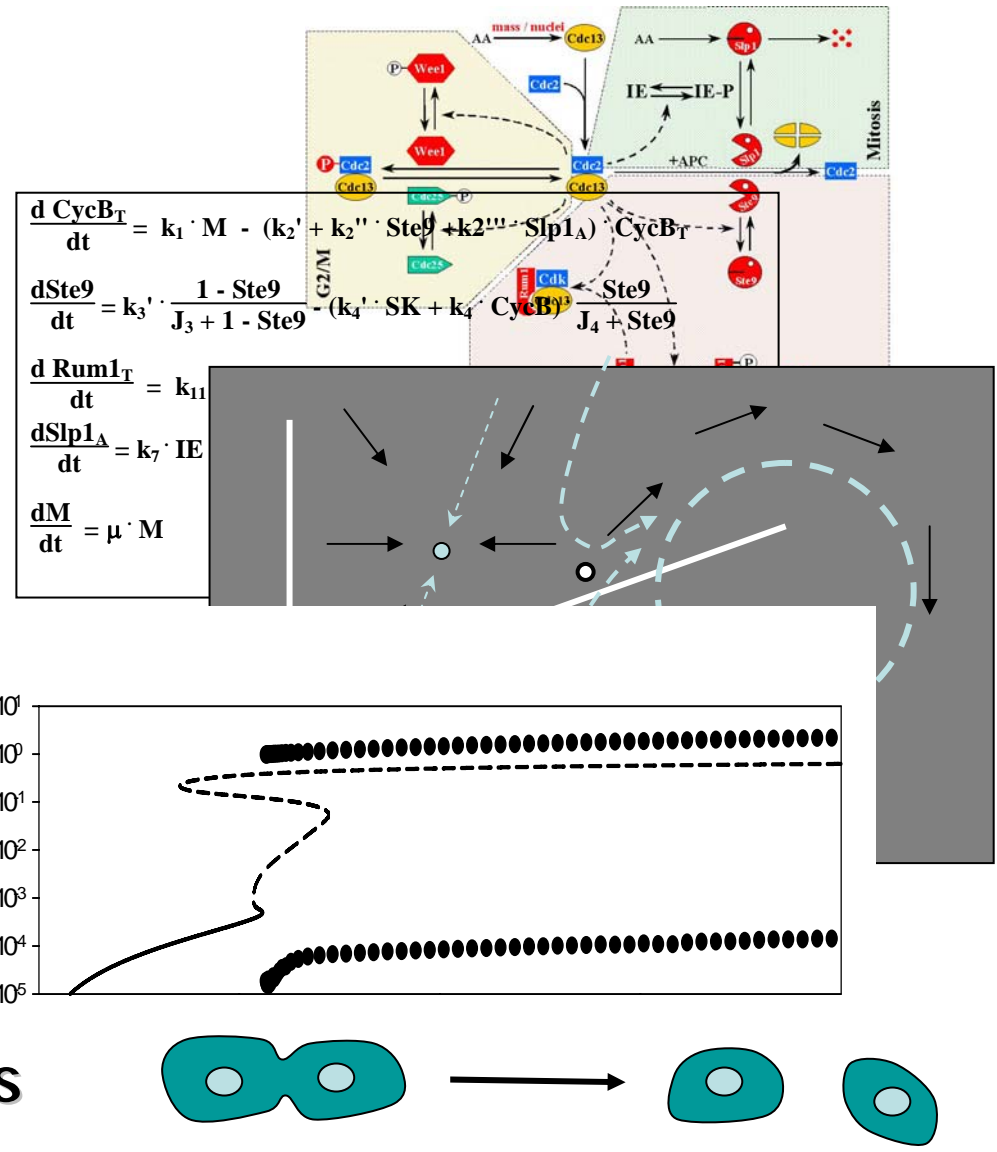
Stable Attractors



Bifurcations



Physiological Properties



The Dynamical Perspective

Molecular Mechanism



Kinetic Equations



Vector Field



Stable Attractors



Bifurcations



Physiological Properties

